

Weighing Lysimeters for Developing Crop Coefficients and Efficient Irrigation Practices for Vegetable Crops

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Abstract. Large, precision weighing lysimeters are expensive but invaluable tools for measuring crop evapotranspiration and developing crop coefficients. Crop coefficients are used by both growers and researchers to estimate crop water use and accurately schedule irrigations. Two lysimeters of this type were installed in 2002 in central California to determine daily rates of crop and potential (grass) evapotranspiration and develop crop coefficients for better irrigation management of vegetable crops. From 2002 to 2006, the crop lysimeter was planted with broccoli, iceberg lettuce, bell pepper, and garlic. Basal crop coefficients, K_{cb} , defined as the ratio of crop to potential evapotranspiration when the soil surface is dry but transpiration is unlimited by soil water conditions, increased as a linear or quadratic function of the percentage of ground covered by vegetation. At midseason, when groundcover was greater than 70% to 90%, K_{cb} was ≈ 1.0 in broccoli, 0.95 in lettuce, and 1.1 in pepper, and K_{cb} of each remained the same until harvest. Garlic K_{cb} , in comparison, increased to 1.0 by the time the crop reached 80% ground cover, but with only 7% of additional coverage, K_{cb} continued to increase to 1.3, until irrigation was stopped to dry the crop for harvest. Three weeks after irrigation was cutoff, garlic K_{cb} declined rapidly to a value of 0.16 by harvest. Yields of each crop equaled or exceeded commercial averages for California with much less water in some cases than typically applied. The new crop coefficients will facilitate irrigation scheduling in the crops and help to achieve full yield potential without overirrigation.

Nearly 1.25 million hectares of vegetables were irrigated in the United States in 2008 (USDA NASS, 2009). Most vegetable crops are shallow-rooted and sensitive to even mild soil water deficits and therefore normally require irrigation for commercial production. Growers thus try carefully to avoid under-irrigation of vegetable crops, although over-irrigation is costly and often reduces crop quality. To schedule irrigations properly, accurate estimates of the water requirements of the vegetable crops are needed.

A dependable method to estimate crop water requirements is a simple procedure whereby water lost by soil evaporation and

plant transpiration, referred to collectively as crop evapotranspiration (ET_c), is calculated by multiplying weather-based estimates of evapotranspiration from a reference crop such as grass (ET_o) or alfalfa (ET_r) by an empirically derived crop coefficient (K_c) used to account for specific conditions of the crop (Allen et al., 1998; Snyder et al., 1987a, 1987b; Wright, 1982). The K_c can be divided into two separate coefficients: a basal crop coefficient, K_{cb} , for crop transpiration, and a soil water evaporation coefficient, K_e , to account for the effects of soil wetting events caused by rain or surface irrigation. The use of a dual crop coefficient is more complicated than a single crop coefficient approach but is recommended when better estimates of ET_c are needed such as when scheduling irrigation for frequent water applications using drip or automated sprinklers (Allen et al., 1998). Although K_c and K_{cb} values have been reported for a number of crops, the list is by no means complete. Accurate K_c values are difficult and expensive to develop, and because many fruits and vegetables are minor crops with a wide range of cultivar differences, most research in this area has focused on crops with large acreage such as wheat, corn, and cotton.

Currently, the most accurate way to estimate crop water use and develop crop coefficients is with precision weighing lysimeters, which has generally been regarded as the standard against which other measures of ET have been compared. Weighing lysimeters determine ET directly by mea-

suring changes in mass of a soil container with plants positioned on a scale or other weighing device. They have been in use for measuring crop water use since the first one was constructed in Coshoctan, OH, in 1937 (Harold and Dreibelbis, 1951). Many others have been built since at locations throughout the United States and other countries with considerable improvements over the years (see Howell et al., 1991 for review), including more sensitive scale systems, computerized data acquisition and control functions (irrigation, drainage, etc.) (Howell et al., 1985), the use of intact soil monoliths (Schneider et al., 1998), and processing methods for better smoothing of noisy lysimeter data (Malone et al., 2000; Vaughn and Ayars, 2009; Vaughn et al., 2007). Examples of crops measured with lysimeters include various field crops such as alfalfa, corn, cotton, soybean, and wheat (e.g., Evett et al., 2000; López-Urrea et al., 2009a) as well as numerous horticultural species such as broccoli (López-Urrea et al., 2009b), cantaloupe (Ayars et al., 1999), garlic (Ayars, 2007), grape (Williams et al., 2003a, 2003b), muskmelon (Lovelli et al., 2005), onion (López-Urrea et al., 2009c; Piccinni et al., 2009), peach (Johnson et al., 2000, 2002), spinach (Piccinni et al., 2009), sweet corn (Ayars et al., 1999), and tomato (Ayars et al., 1999; Phene et al., 1985).

Accuracy of lysimeter ET measurements varies depending on area and mass of the lysimeter as well as the type of scale system used, but many are precise within 0.02 to 0.05 mm of water use (Howell et al., 1991). This

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high a resolution requires the ability to detect very small weight changes in large soil volumes. For example, to measure 0.05 mm of water use, the lysimeter must detect a weight change of only 0.01 kg·m⁻² of soil surface area. Large counterweights are typically used to offset the container and soil mass to permit precise measurements of soil evaporation and crop transpiration. Crop growth within the lysimeter tank should duplicate the field conditions where the data will be collected, and the crop surrounding the lysimeter should be similar to that inside the lysimeter (Allen et al., 1991; Pruitt and Lourence, 1985). The lysimeter should be situated within a field that is as level as possible and away from any obstructions that potentially alter radiation and wind patterns. Many investigators recommend an upwind fetch, with the same uniform crop as in the lysimeter, for a distance of greater than 50 m and a site area of at least 1 ha.

Two large weighing lysimeters, one for crops and one for grass, were constructed in 2002 at the University of California West Side Research and Extension Center (WSREC) located near Five Points, CA. The climate at the Center is Mediterranean-like with cool winters and an average annual precipitation of 215 mm (1983 to 2005). The project is long-term and is aimed at developing crop coefficients for vegetable crops produced in the semiarid San Joaquin Valley of central California. The San Joaquin Valley is one of the most productive agricultural regions in the world and is a leading producer of many vegetable crops. This article briefly reviews the use of the weighing lysimeters between 2002 and 2006 in development of crop coefficient curves for broccoli, iceberg (head) lettuce, bell pepper, and garlic.

LYSIMETER CONSTRUCTION AND DESIGN

Each lysimeter consists of a 2 m × 2 m × 2.25-m deep steel soil tank positioned on a mechanical tank scale (Model FS-4; Cardinal Scale Manufacturing Co., Webb City, MO) housed inside an underground steel enclosure with a concrete floor (Fig. 1). The lysimeters are similar in design to the type described by Lourence and Moore (1991). They were purchased from Precision Lysimeters (Red Bluff, CA) in 2001 at a cost of \$47,000 each, which included the steel enclosure and tank, the scale system, an access hatch and ladder, and delivery. Additional costs included soil excavation, installation of the concrete pads, crane rental to position the steel tanks and enclosures at the site, water and power supply to the lysimeters, data loggers, and labor.

The scale is a double wishbone type with a transverse lever assembly, which extends out into an underground access chamber to accommodate counterweights (Fig. 1D). The scale system ratio is equal to 100:1 at the point of counterweight and therefore 10 kg of lead weight counterbalances ≈1000 kg in the soil tank. A precision load cell is located on a pull rod connecting the shelf lever to the weigh beam, producing a nominal signal of

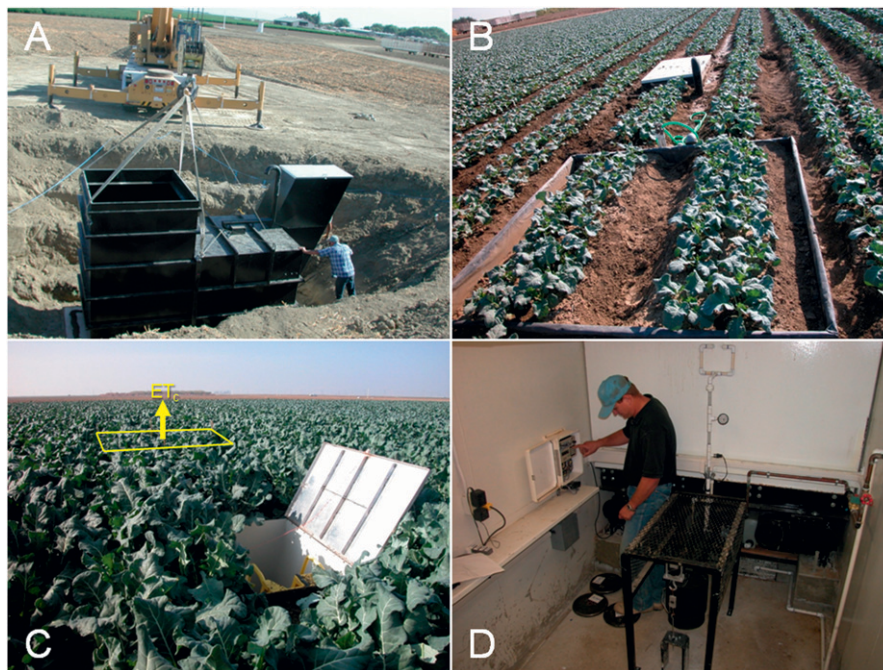


Fig. 1. (A) Installation of a steel enclosure for the crop lysimeter. The crop lysimeter was first planted with broccoli on 19 Aug. 2002 and is shown here at (B) 38 d and (C) 86 d after planting. (D) Inside the lysimeter enclosure. A 14-t soil tank is placed on a counterbalanced scale system and a data logger is used to monitor weight changes in the lysimeter tank resulting from crop evapotranspiration.

4 $\mu\text{V}\cdot\text{kg}^{-1}$ of weight change on the soil tank. More sensitive load cells are available, but the less sensitive model gives more margin of protection from overload. The weigh beam is scaled from 0 to 1500 kg in 0.1-kg increments equivalent to 0.025 mm of water weight change on the soil tank. The load cell was calibrated by placing known weights in the range of 20 to 200 kg on the lysimeter surface.

Soil at the site is a Panoche clay loam (Typic Torriorthents) with relatively uniform water retention characteristics and high water-holding capacity averaging over 425 mm in the top 2.5 m (Nielsen et al., 1973). The soil was carefully removed in 0.3-m increments during excavation for the lysimeters and repacked in the soil tanks and around the enclosures at approximately the same depth and soil density as the surrounding field. The gap between the soil tank and enclosure wall of the lysimeters is less than 2 cm on all sides with the top edges of each located ≈5 cm above level field grade. The gaps were covered with EPDM nylon fabric glued to the inside of the soil tank and outside to the outer enclosure wall with rubber cement. The fabric was looped upward ≈0.5 cm above the tank edge to avoid any tension on the soil tanks. Soil above each underground access chamber is ≈0.95 m deep. Sufficient soil depth on all sides of the soil tanks is critical to maintain similar soil temperatures between the field and soil tanks and to establish a healthy crop and adequate drainage in the vicinity of the field surrounding the tanks.

The basic data obtained from the lysimeters are weight loss resulting from crop or grass ET and weight gain resulting from precipitation

and irrigation, in which 4 kg equals 1 mm of water over the 4-m² surface area. Weight changes measured by the load cell are recorded hourly using a Campbell Scientific CR3000 data logger, upgraded from a CR-21X in 2006 (Logan, UT). An irrigation water supply tank is hung on the underside of the soil tank and refilled nightly, between 2400 HR and 0100 HR to a reference weight to replace any water consumed the previous day. The soil tank is irrigated from the supply tank each time the lysimeter weight decreases by 4 kg (i.e., 1 mm of water use). That way, irrigations involve only a transfer of water from the supply tank to the soil tank, resulting in no irrigation weight changes during the day, and the lysimeter weight declines continuously as water is transpired by the plants and evaporated from the soil surface (Phene et al., 1989). Irrigation is applied by drip tubing installed 0.2 m deep in the crop lysimeter and 0.1 m deep in the grass lysimeter and measured by a flow meter (IR-Opflow Type 1; JLC Intl., New Britain, PA). Excess rainfall or irrigation that percolates to the bottom of the soil tank drains by gravity through a polyvinyl chloride drainage manifold and is measured using a Campbell Scientific model TE525MM rain gauge (Logan, UT) located on the floor under the tank.

The lysimeters are each located near the center of adjacent, laser-leveled 1.8-ha fields (≈90 m × 200 m). The fields are surrounded by other fields planted with various low annual crops such as cotton and processing tomato. The crop lysimeter and field were planted with broccoli in Fall 2002, iceberg lettuce in Fall 2004, bell pepper in spring to Summer 2005, and garlic in Winter to Summer 2006. Fertilization, thinning, and weed and pest control

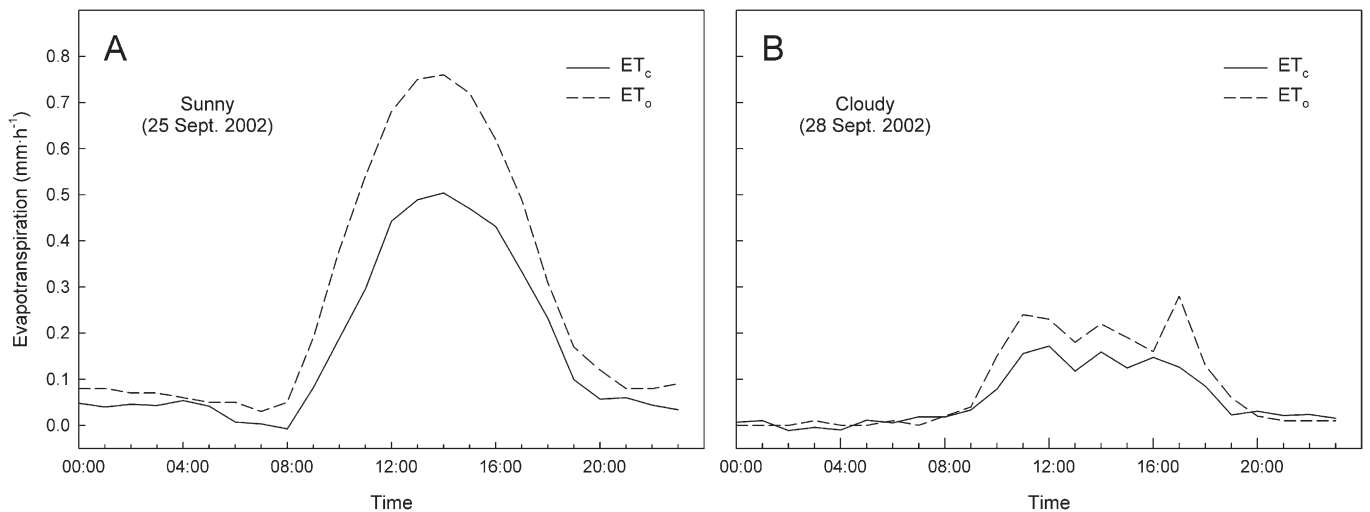


Fig. 2. Hourly rates of crop (broccoli) evapotranspiration (ET_c) and reference evapotranspiration (ET_o) on a sunny day (A) and a cloudy day (B) near Five Points, CA.

were done following standard cultural practices for the region. The fraction of ground covered or shaded by vegetation (f_c) in the lysimeter was measured periodically each growing season using an ADC multispectral camera (TetraCam, Chatsworth, CA) mounted on a frame 1.5 m above the bed surface and imaging–editing software provided with the camera, following the procedures outlined by Trout et al. (2008). The lysimeter and field were also planted with bell pepper in 2003 and lettuce in Spring 2004, but crop growth in and around the lysimeter on these dates was non-uniform; therefore, the data were not used to develop crop coefficients. The grass field was planted with tall fescue (*Festuca arundinacea* Schreb.) in Fall 2002. The grass is irrigated by subsurface drip laterals spaced 0.3 m apart and 0.1 m deep in the vicinity of the lysimeter and by pop-up sprinklers on the outer edges of the field and is mowed weekly, or as needed in cooler months, to a height of 0.1 m.

A California Irrigation Management Information System (CIMIS) weather station (#2) is located 7 m from the grass lysimeter. The ASCE standardized reference evapotranspiration equation (ASCE-EWRI, 2005) was used to calculate ET_o with weather data downloaded from the CIMIS web site (<http://www.cimis.water.ca.gov>). Crop coefficients were calculated as the ratio of daily ET_c measured on the crop lysimeter to ET_o calculated from the CIMIS weather station data. The K_c calculations were based on CIMIS ET_o rather than lysimeter ET_o because the intended function of the values is for estimating crop ET from weather data (Allen et al., 1998). The grass lysimeter was used primarily to evaluate CIMIS ET_o .

DEVELOPING CROP COEFFICIENTS

On normal cloudless days in central California, the crop lysimeter typically generated smooth daily ET graphs with minimal noise (Fig. 2A). On cloudy days, on the other hand, the lysimeter data were more variable,

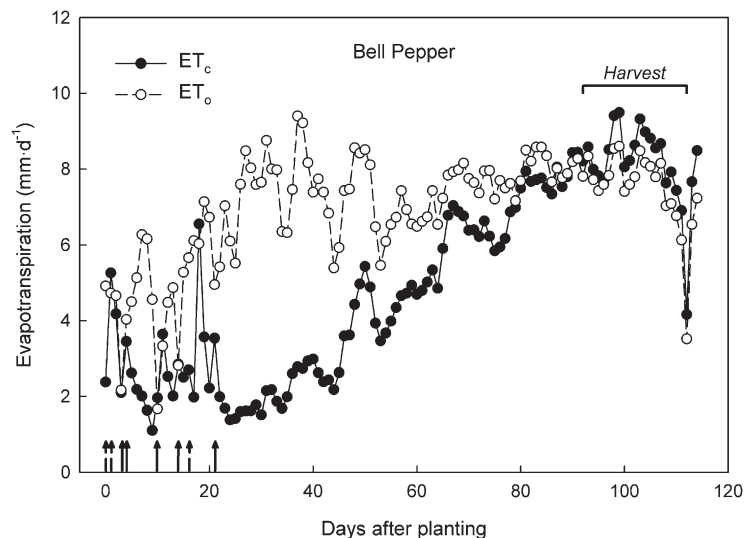


Fig. 3. Daily rates of crop (bell pepper) evapotranspiration (ET_c) and reference evapotranspiration (ET_o) from planting (25 Apr. 2005) to harvest (25 July to 16 Aug. 2005). Solids arrows on the x-axis indicate rain events and broken arrows indicate days the crop was irrigated by sprinklers. Data are from Trout and Gartung (2006).

as light conditions changed over the course of the day, but ET_c generally followed the same pattern as ET_o , resulting in consistent day-to-day K_c values (i.e., ratio of ET_c to ET_o) (Fig. 2B). Hourly ET_c and ET_o values were summed each day to calculate daily K_c . Using the data in Figure 2, daily K_c values on 25 and 28 Aug. 2002 were 0.63 and 0.69, respectively.

A typical seasonal relationship between ET_c and ET_o is illustrated in Figure 3 for bell pepper. Daily ET_c , in this case, ranged from less than 2 $mm \cdot d^{-1}$, early in the season, when plants were small and the soil surface was dry, to ≈ 8 to 9 $mm \cdot d^{-1}$ during the peak ET period in late July to early August, when plants reached full effective cover and the peppers were ready for harvest. The effects of a wet soil surface from sprinklers and rain are evident during the first 20 d after planting by the fact that ET_c after each event was nearly

equal to or greater than ET_o . A method for estimating the crop coefficient for soil water evaporation, K_{cb} , most important immediately after rain or surface irrigation, is described elsewhere (Allen et al., 1998).

The crop coefficient curves computed from daily ET_c and ET_o data are shown in Figures 4 through 7. In each case, the data were fit with a FAO segmented basal crop coefficient, K_{cb} , curve at three or four stages of crop growth, including the initial stage ($K_{cb \text{ ini}}$) that starts at planting and goes to when $\approx 10\%$ of the soil surface is covered by green vegetation, the crop development stage ($K_{cb \text{ dev}}$) that runs from 10% cover to full effective cover (defined in row crops as the stage when leaves between rows begin to intermingle or, if no intermingling occurs, when plants reach nearly full size), the mid-season stage ($K_{cb \text{ mid}}$) that covers the period

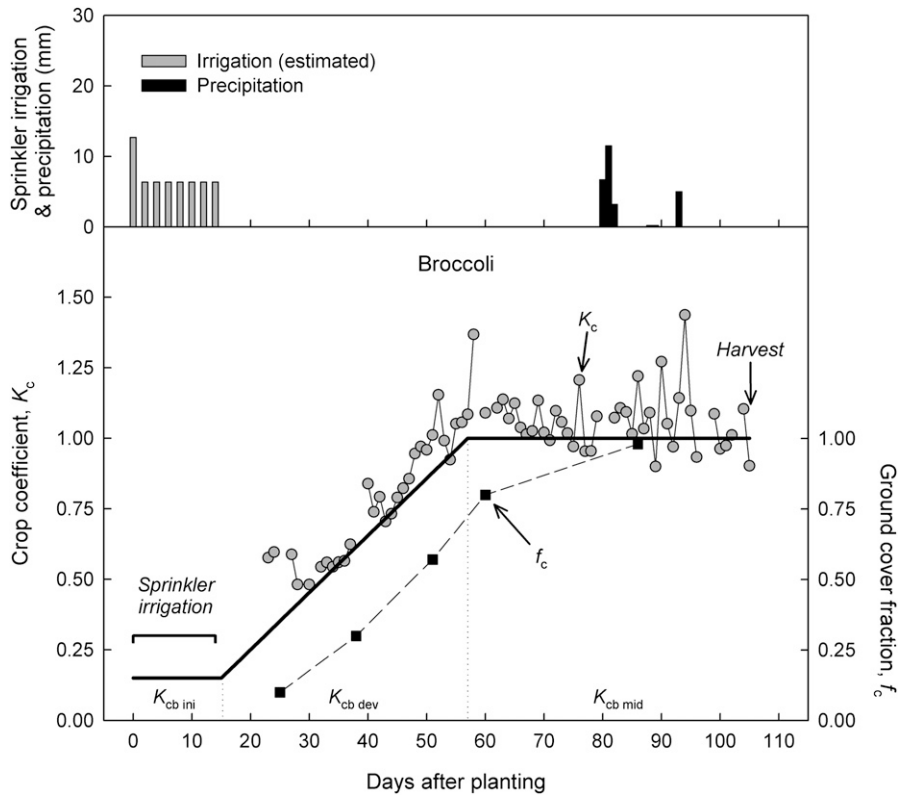


Fig. 4. Daily crop coefficients (K_c) and vegetative ground cover fraction (f_c) for broccoli from 23 d after planting (planted 19 Aug. 2002) to harvest (2 Dec. 2002). The heavy line represents the FAO segmented basal crop coefficient (K_{cb}) curve at three stages of crop growth (initial period, $K_{cb\ ini}$; crop development period, $K_{cb\ dev}$; and midseason period, $K_{cb\ mid}$).

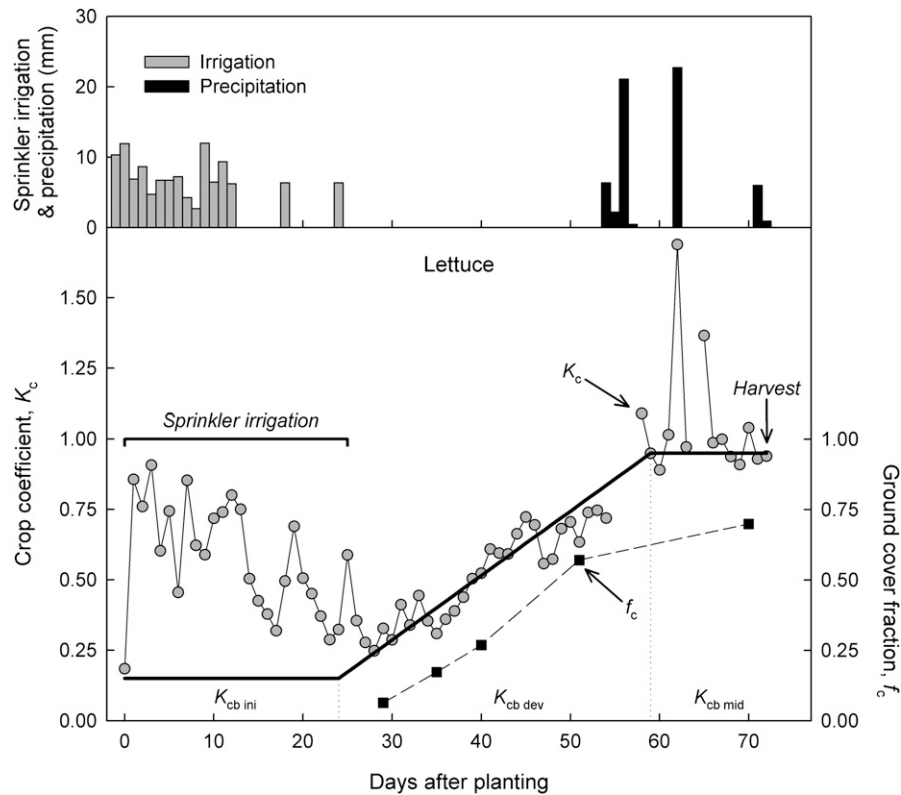


Fig. 5. Daily crop coefficients (K_c) and vegetative groundcover fraction (f_c) for iceberg lettuce from planting (24 Aug. 2004) to harvest (4 Nov. 2004). The heavy line represents the FAO segmented basal crop coefficient (K_{cb}) curve at three stages of crop growth (initial period, $K_{cb\ ini}$; crop development period, $K_{cb\ dev}$; and midseason period, $K_{cb\ mid}$). Data are from Trout and Gartung (2006).

between full effective cover to full maturity (initiation of flowering in many crops), and the late-season stage ($K_{cb\ late}$) that runs from full maturity to leaf senescence or harvest. The $K_{cb\ ini}$ of each curve was set at 0.15 as recommended for vegetables in the FAO-56 publication (Allen et al., 1998). The midseason stage is often short in vegetable crops and in some cases may be the final stage if crops are harvested fresh for green vegetation (e.g., lettuce). The K_{cb} reaches its maximum value at midseason.

Broccoli. Broccoli (*Brassica oleracea* L. ‘Captain’) was transplanted in the crop lysimeter and field on 19 Aug. and harvested 2 Dec. 2002. Broccoli is produced primarily in fall and winter months in central California. Plants were grown in double rows on 1.0-m wide raised beds with seedlings spaced ≈ 0.30 to 0.35 m apart. The transplants were established to stand with sprinklers. Plants received a total of 198 mm of water over the season by subsurface drip irrigation plus an additional 22 mm of rain. In comparison, López-Urrea et al. (2009b) determined that the total consumptive water use for fall-planted, sprinkler-irrigated broccoli was 359 mm, or 249 mm without soil evaporation, for a period of 109 d after transplanting in central Spain.

No lysimeter data were available in our study during the first 22 d after planting. However, assuming $K_{cb\ ini}$ was equal to 0.15, K_{cb} appeared to increase from ≈ 15 to 57 d after planting and reached 1.0 at midseason (Fig. 4), which is 0.06 higher than the climate-adjusted $K_{cb\ mid}$ value listed for broccoli in FAO-56 (Table 1). Thus, ET_c estimates calculated using FAO-56 differed from actual lysimeter ET_c by a season total of only 13 mm. There was little evidence of a late-season stage for K_{cb} , not surprising because leaves on the plants were still green and succulent when the broccoli florets were harvested.

Broccoli harvested from the lysimeter averaged 0.32 kg (fresh weight) of marketable field-cut florets per plant, which is equivalent to 19.2 t·ha⁻¹ and higher than the 15 t·ha⁻¹ average for California (LeStrange et al., 1996). The crop also required considerably less irrigation than the 550 to 600 mm typically applied to the crop according to a local grower advisory group.

Lettuce. Iceberg lettuce (*Lactuca sativa* L.) was planted on 24 Aug. using pelleted seed and harvested on 4 Nov. 2004. Lettuce is produced primarily in fall and winter months in central California. Plants were grown in double rows on 1-m wide raised beds and spaced ≈ 0.2 m apart after thinning. The field was sprinkler-irrigated daily beginning 2 d before and 12 d after planting until the seedlings emerged and at 18 and 24 d after planting to prepare the field for thinning and weeding. As a result, K_c values were high, in the range of 0.29 to 0.91, during the initial stage of plant development as a result of soil evaporation from frequent soil surface wetting (Fig. 5).

The soil surface was dry during most of the crop development stage where K_{cb} increased between 24 and 59 d after planting as

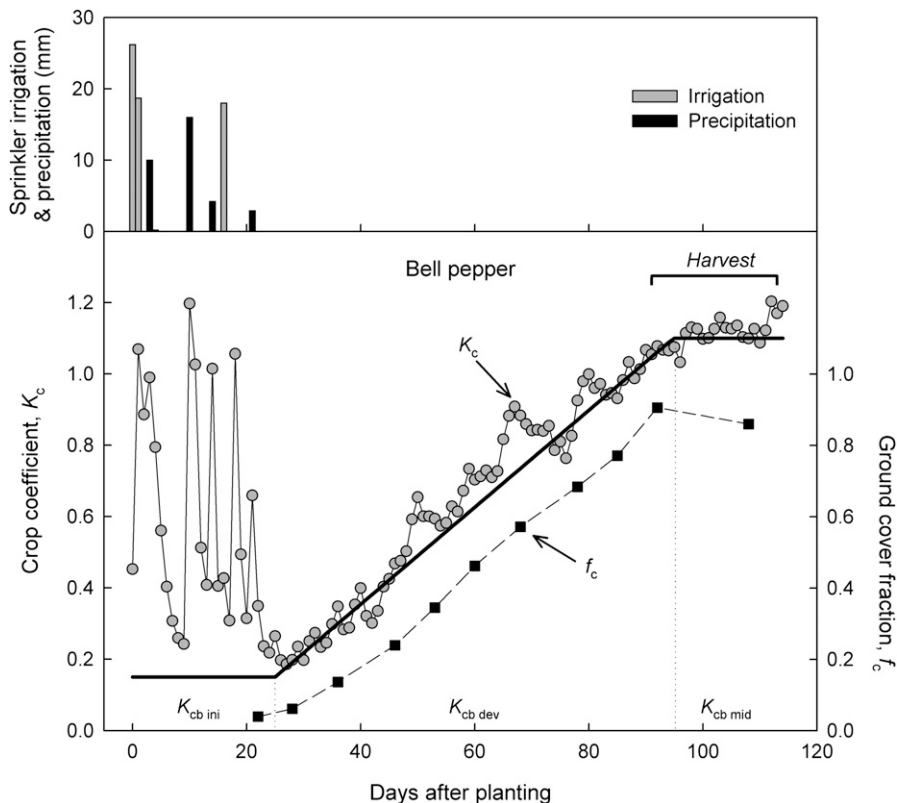


Fig. 6. Daily crop coefficients (K_c) and vegetative groundcover fraction (f_c) for bell pepper from planting (25 Apr. 2005) to harvest (25 July to 16 Aug. 2005). The heavy line represents the FAO segmented basal crop coefficient (K_{cb}) curve at three stages of crop growth (initial period, $K_{cb\ ini}$; crop development period, $K_{cb\ dev}$; and midseason period, $K_{cb\ mid}$). Data are from Trout and Gartung (2006).

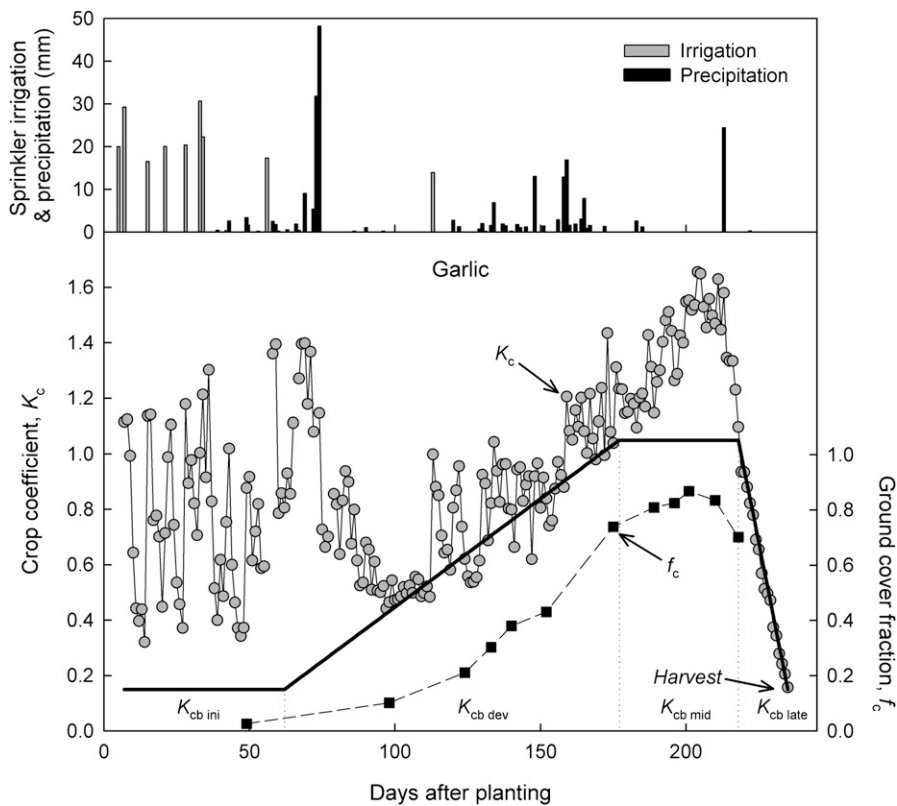


Fig. 7. Daily crop coefficients (K_c) and vegetative groundcover fraction (f_c) for garlic from planting (25 Oct. 2005) to harvest (12 June 2006). The heavy line represents the FAO segmented basal crop coefficient (K_{cb}) curve at four stages of crop growth (initial period, $K_{cb\ ini}$; crop development period, $K_{cb\ dev}$; midseason period, $K_{cb\ mid}$; and late-season period, $K_{cb\ late}$). Data are from Ayars (2007).

a function of the soil surface covered by the crop canopy. Peak K_{cb} at midseason was 0.95 with a final ground cover fraction at harvest of only 70%, which is 0.07 higher than the climate-adjusted $K_{cb\ mid}$ value listed for lettuce in FAO-56 (Table 1). Two spikes in K_c during the relatively short (14 d) midseason stage were notable and likely the result of heavy rain. When $K_{cb\ mid}$ is less than 1.0, frequent wetting by rain or irrigation often increases K_c at midseason as a result of combined effects of continuously wet soil, evaporation off the plants at interception, and less boundary layer resistance as a result of roughness of the vegetation (Allen et al., 1998).

Lettuce yield in the field was 54 t·ha⁻¹, which, like broccoli, was higher than the 40 t·ha⁻¹ average for California (Jackson et al., 1996). Plants received a total of 117 mm of water by sprinklers, 98 mm of water by subsurface drip irrigation, and 60 mm of rain, again lower than the amount typically applied in the region but comparable to the amount applied to lettuce in the central coast of California (Jackson et al., 1996).

Peppers. Bell pepper (*Capsicum annuum* L. 'Baron') was transplanted on 25 Apr. and harvested between 25 July and 16 Aug. 2005. Peppers are planted in spring and harvested as a summer crop in California's San Joaquin Valley. Plants were grown in a single row on 1-m wide raised beds and spaced 0.25 m apart. The field was irrigated by sprinklers twice the first 2 d after planting and once at 16 d after planting; it also rained 4 d during the first 3 weeks after planting. The effects of the wetting events are evident as K_c increased sharply after each event, as high as 1.20 (Fig. 6).

The soil surface was dry during the crop development stage, a period that lasted ≈70 d, as ground cover increased from ≈5% to 90%. Maximum K_{cb} at midseason was 1.10, reached shortly after the first pepper harvest at 95 d after planting, and was similar to the adjusted value of 1.06 listed for bell pepper in FAO-56 (Table 1). The midseason stage was short and lasted only 18 d until harvest was done.

With no rain or sprinkler irrigation after the initial period, the soil surface was dry and therefore $K_{c\ dev/mid}$ was more or less equal to $K_{cb\ dev/mid}$. Allen et al. (1998) defined K_{cb} as the ratio of ET_c over ET_o when the soil surface is dry but transpiration is unlimited by soil water availability. Under limited soil water conditions, e.g., as a result of drought or high soil salinity, K_c declines and K_{cb} must be adjusted using a dimensionless stress coefficient, K_s , dependent on available soil water [see Allen et al. (1998) and Doorenbos and Kassam (1979) for details]. Once pepper irrigation was ended after harvest, K_c declined within 25 d to 0.76 before any signs of leaf wilt (data not shown).

Marketable pepper yield in the field totaled 38 t·ha⁻¹, close to the 41 t·ha⁻¹ average for California (Hartz et al., 2007). Plants received a total of 63 mm of water by sprinklers, 561 mm of water by subsurface drip irrigation, and 33 mm of rain.

Garlic. Garlic (*Allium sativum* spp. *sativum* L.) cloves were planted on 25 Oct. 2005 and harvested 12 June 2006. Garlic is mostly planted in early winter in California and harvested in summer. Plants were grown in double rows on 1-m wide raised beds at a density of ≈ 60 plants per meter. The field was sprinkler-irrigated until stand and later irrigated by subsurface drip. Irrigation was cutoff at 3 weeks before harvest (22 May) to dry the beds.

The garlic crop developed considerably slower than the other vegetables and required ≈ 170 to 190 d of growth to reach 70% to 80% ground cover (Fig. 7). By this point, plants were irrigated only another 20 d before irrigation was ended to begin drying the soil and garlic bulbs for harvest. Unlike the other vegetable crops, garlic K_c never leveled off, even when ground cover exceeded 80%. The $K_{cb\ mid}$ value (1.0) illustrated in Figure 7 was chosen as the point at which 80% cover was reached; however, maximum K_{cb} was actually ≈ 1.3 . When the lysimeter was grown with garlic, daily minimum relative humidity at $K_{cb\ mid}$ averaged 25% and mean daily wind speed was $3.6\ m\ s^{-1}$, which partly accounts for the high K_c values observed at effective

full cover (Table 1). Garlic K_c , determined by an eddy covariance method, reached a maximum value of 1.2 to 1.3 under semiarid condition in Spain and declined to ≈ 0.6 at harvest (Villalobos et al., 2004). In our study, garlic K_c at harvest ($K_{c\ end}$) was 0.16 and similar to $K_{cb\ ini}$, indicating the surface soil was very dry and the plant leaves were

completely desiccated. The $K_{cb\ end}$ listed for garlic in FAO-56 is 0.60, and 0.68 after adjusting for climate, a value reached ≈ 10 d before harvest in the lysimeter.

Marketable yield of the garlic was $20\ t\ ha^{-1}$, slightly higher than the $18\ t\ ha^{-1}$ average for California (California Agricultural Statistical Service, 2006). Crop water

Table 1. Midseason basal crop coefficients ($K_{cb\ mid}$) for vegetable crops in the San Joaquin Valley of California.

Parameter	Broccoli	Lettuce	Bell pepper	Garlic
Lysimeter $K_{cb\ mid}$	1.00	0.95	1.10	1.00
FAO $K_{cb\ mid}^z$	0.95	0.90	1.00	0.90
Midseason conditions				
Wind speed, u_2 ($m\ s^{-1}$)	1.9	1.5	2.7	3.0
RH _{min} (%)	47	52	26	35
Plant height, h	0.6	0.3	0.6	0.6
Adjusted $K_{cb\ mid}^y$	0.94	0.88	1.06	0.95
Midseason stage				
Days after planting	57–105	59–72	95–114	177–218
Dates	15 Oct. to 2 Dec. 2002	22 Oct. to 4 Nov. 2004	29 July to 16 Aug. 2005	15 Apr. to 26 May 2006

^zValues from FAO Irrigation and Drainage Paper 56 (Allen et al., 1998).

^yFAO $K_{cb\ mid}$ values [$K_{cb\ mid(Tab)}$] are adjusted for climate when minimum relative humidity (RH_{min}) at the midseason growth stage differs from 45% and wind speed (u_2) at 2 m height over grass is larger or smaller than $2\ m\ s^{-1}$, as follows: $K_{cb\ mid} = K_{cb\ mid(Tab)} + [0.04(u_2 - 2) - 0.004(RH_{min} - 45)] (\frac{h}{3})^{0.3}$ (Allen et al., 1998).

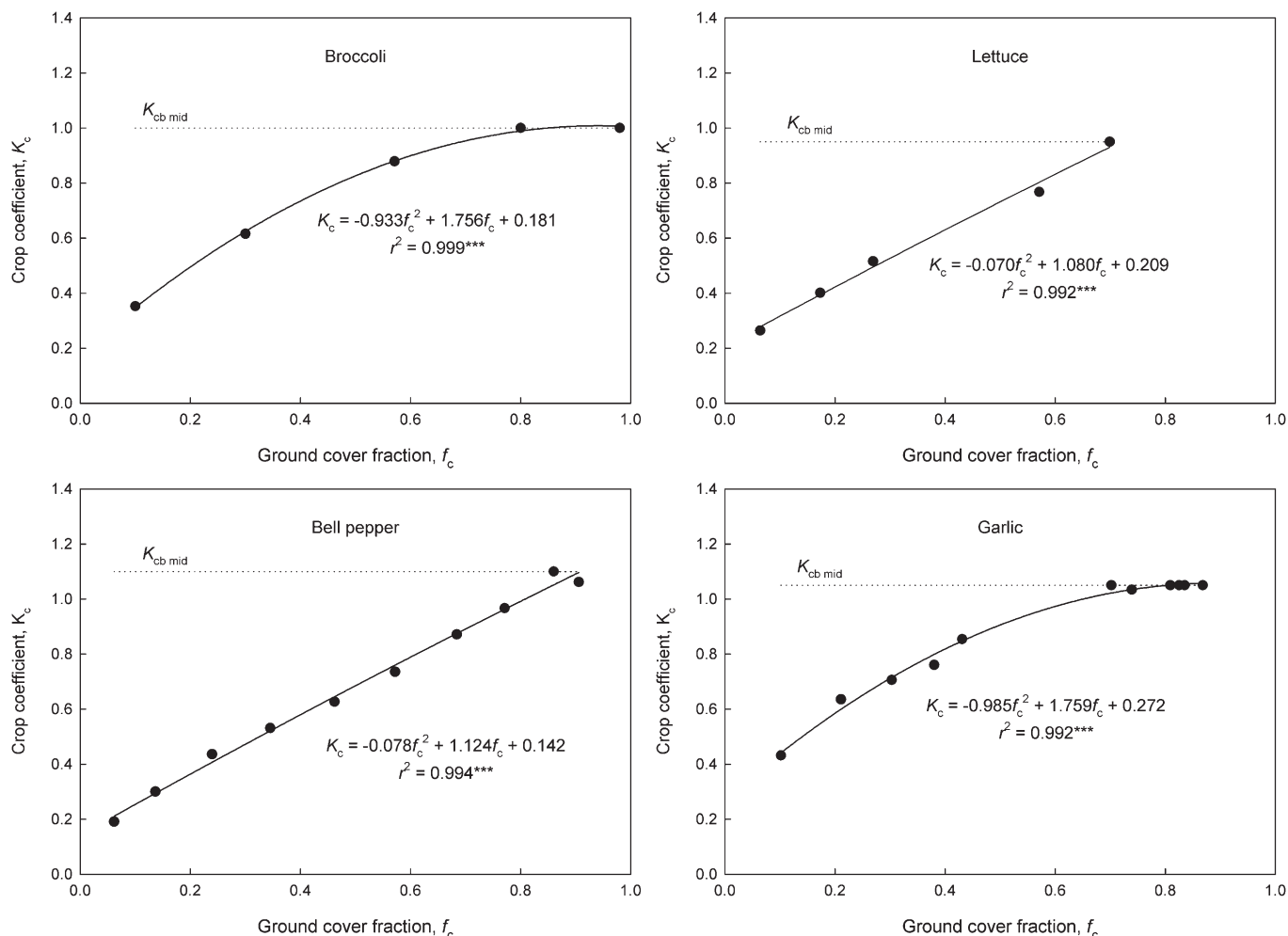


Fig. 8. Relationship between the basal crop coefficient, K_{cb} , and ground cover fraction, f_c , in broccoli, iceberg lettuce, bell pepper, and garlic. Data are from Figures 4 through 7. $***P < 0.001$.

use measured by the lysimeter between 1 Mar. (142 d after planting) and irrigation cutoff on 22 May totaled 425 mm with 108 mm of rain during this period.

RELATIONSHIP BETWEEN BASAL CROP COEFFICIENTS AND GROUND COVER

Recent lysimeter studies have explored the relationship between crop coefficients and ground cover in various horticultural crops, including vegetables, fruit trees, and grapevines, and have found that K_{cb} is often linearly correlated to canopy light interception or shaded area (Johnson et al., 2000, 2002; Trout et al., 2008; Williams and Ayars, 2005). Generalized relationships of this sort would allow weather-based irrigation scheduling for a wide range of horticultural crops based on simple canopy measurements or possibly based on remotely sensed vegetation indices (Trout and Johnson, 2007; Trout et al., 2008). Because light interception other than at mid-day and aerodynamic roughness of the plant surface will depend on the canopy structure, adjustments to these simple linear models may be needed for taller crops (Allen and Pereira, 2009).

Gratten et al. (1998) developed non-linear relationships between ground cover and crop coefficients for vegetable and row crops in California using the Bowen ratio method to determine crop ET. They concluded that K_c changed as a quadratic function of percentage ground cover. Quadratic relationships between K_{cb} and ground cover fraction, f_c , were also evident when plotted using the lysimeter data, although linear fits were good before midseason, especially when the crop's mid-season was short, e.g., in lettuce and bell pepper (Fig. 8).

Allen and Pereira (2009) recently formalized the FAO-56 procedure for estimating K_c as a function of fraction of ground cover and crop height using a density coefficient, K_d , whereby K_d is multiplied by K_c representing full cover conditions, $K_{cb\ full}$, to produce a K_{cb} representing the actual condition of ground cover. The authors note that the method does not replace ET measurement for developing crop coefficient curves, but it does provide a means to estimate change in K_c values with increases (or decreases, e.g., as a result of insect herbivory) of ground cover.

COMPARISON OF LYSIMETER AND CIMIS EVAPOTRANSPIRATION

CIMIS ET_o was evaluated in 2004 and 2005 using data collected from the grass lysimeter and the CIMIS weather station (Vaughn et al., 2007). When daily ET_o was less than 6 mm-d⁻¹, ET_o values calculated using either the Pruitt-Doorenbos (Pruitt and Doorenbos, 1977) or the Penman-Monteith (Allen et al., 1989) models were in good agreement with daily ET_o measured by the lysimeter. However, when ET_o was greater than 6 mm-d⁻¹, CIMIS predictions of ET_o were less than lysimeter ET_o and the relation-

ship between the two was slightly non-linear. The importance of this difference is illustrated in measurement of K_c for garlic. In this case, ET demands were high as the crop approached midseason. Crop coefficients were 0.19 lower on average if lysimeter ET_o was used to calculate garlic K_c whenever CIMIS ET_o was higher than 6 mm-d⁻¹ and the crop was irrigated.

Vaughn et al. (2007) also found that the correlation between CIMIS and lysimeter ET_o was poor at night. Because ET_o is sometimes substantial at night, identification of specific atmospheric conditions on such nights may lead to better weather-based predictions.

SUMMARY AND CONCLUSIONS

Weighing lysimeters are useful tools for measuring crop water requirements and developing K_c curves in horticultural crops. Crop coefficient curves were developed using the WSREC lysimeters in broccoli, lettuce, bell pepper, and garlic in central California. Basal crop coefficients, K_{cb} , which represent primarily the transpiration component of crop ET, increased linearly or curve linearly with crop development and, with the exception of garlic, reached maximum K_{cb} once ground cover was greater than 70% to 90%. When the data were fit using the FAO segmented approach, basal crop coefficients at midseason or $K_{cb\ mid}$ were within 0.04 to 0.07 of those listed for each crop in FAO-56; however, the $K_{cb\ end}$ value listed for garlic differed considerably and was 0.5 lower in the lysimeter. This latter difference may reflect the level in which the crop is dried before harvest. It was not possible to determine basal crop coefficients during initial stages of crop growth, $K_{cb\ ini}$, because frequent sprinkler irrigation or rain was needed at this stage to establish the crops. A possible method to determine $K_{cb\ ini}$ might be to measure lysimeter ET before planting, before any rain or surface irrigation water is applied.

Results of this work are helping California's farmers select irrigation systems and management strategies that can increase profitability for growing crops in the San Joaquin Valley and increase economic value per unit of water used. It also helps irrigation managers and consultants make better recommendations regarding irrigation in the region. Improving irrigation management reduces seasonal water requirements, allowing farmers to maintain yields with less water, even in the event of reduced water allocations, and perhaps use the saved water for production of other crops. Many benefits result from application of improved K_c values, in particular higher irrigation water use efficiency, especially when used in conjunction with proper irrigation system maintenance. Using 369,000 ha of irrigated vegetables harvested in California in 2008 as a basis, and assuming that an average of 600 mm of water is typically applied per crop, a 10% water savings from the use of crop coefficients and more accurate irrigation scheduling practices could result in 221,000,000 m³ of water saved per year.

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